

EXISTENCE AND MULTIPLICITY OF SOLUTIONS FOR A DISCRETE FOURTH-ORDER BOUNDARY VALUE PROBLEM

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Abstract. The purpose of this paper is to establish some results on the existence of multiple solutions for a discrete fourth-order problem. The approach is based on variational methods. Some applications and examples are provided to illustrate the obtained results.

Keywords: Discrete equation, fourth-order boundary value problem, multiple solutions, variational methods.

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1 Introduction

Recently, some authors have studied problems of the type

$$\begin{cases} \Delta^4 u(t-2) + \eta \Delta^2 u(t-1) - \zeta u(t) \\ \quad = \lambda f(t, u(t)) + \mu g(t, u(t)) + h(u(t)), & t \in [a+1, b+1]_{\mathbb{Z}}, \\ u(a) = \Delta^2 u(a-1) = 0, \quad u(b+2) = \Delta^2 u(b+1) = 0, \end{cases} \quad (D_{\lambda, \mu}^{f, g, h})$$

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where Δ denotes the forward difference operator, defined by

$$\begin{aligned}\Delta u(t) &= u(t+1) - u(t), \\ \Delta^n u(t) &= \Delta(\Delta^{n-1}u(t)),\end{aligned}$$

a, b are two fixed integers, $[a+1, b+1]_{\mathbb{Z}}$ is the discrete interval $\{a+1, a+2, \dots, b+1\}$, $f, g: [a+1, b+1]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$ are two functions which are continuous in their second variable, and $h: \mathbb{R} \rightarrow \mathbb{R}$ is a strictly monotone Lipschitz continuous function with a Lipschitz constant $L > 0$ satisfying $h(0) = 0$. Moreover, the four real parameters η, ζ, λ and μ are such that $\lambda > 0$, $\mu \geq 0$, $\eta^2 + 4\zeta \geq 0$,

$$\eta < 8 \sin^2 \frac{\pi}{2(b-a+2)} \quad \text{and} \quad \zeta + 4\eta \sin^2 \frac{\pi}{2(b-a+2)} < 16 \sin^4 \frac{\pi}{2(b-a+2)}.$$

In the last decades, much attention has been concentrated on fourth-order difference equations which are derived from various discrete elastic beam problems. Some of the significant results on the existence and multiplicity of solutions for discrete fourth-order boundary value problems have been obtained using classical methods, such as fixed point theory and fixed point index theory [1, 2, 3, 9, 11, 12, 22], critical point theory [8, 13, 19], and the Krein–Rutman theorem and bifurcation theory [16, 17, 18].

In [3], Anderson *et al.*, using the Guo–Krasnosel’skii fixed point theorem and the Leggett–Williams theorem, studied the existence, multiplicity and non-existence of non-trivial solutions to the following problem

$$\begin{cases} \Delta^4 u(t-2) + \eta \Delta^2 u(t-1) = \lambda f(t, u(t)), & t \in [a+1, b+1]_{\mathbb{Z}}, \\ u(a) = \Delta^2 u(a-1) = 0, \quad u(b) = \Delta^2 u(b-1) = 0. \end{cases} \quad (1.1)$$

In [12], applying variational methods and critical point theory, some multiplicity results for discrete fourth-order boundary value problems with four parameters were established. Some closely related problems have been also recently studied in the papers [14, 15].

Let us consider the following condition.

- (j₁) Let $h: \mathbb{R} \rightarrow \mathbb{R}$ be a strictly monotone function such that $h(0) = 0$, which is Lipschitz continuous with constant $L > 0$; that is, for all $x_1, x_2 \in \mathbb{R}$ we have

$$|h(x_1) - h(x_2)| \leq L|x_1 - x_2|.$$

We further assume that $0 < L < \frac{1}{2}\varepsilon_1$, where ε_1 will be introduced later.

Here, we deal with the problem $(D_{\lambda, \mu}^{f, g, h})$ when the continuous functions f and g have the subcritical growth and, via variational methods, we obtain the existence of at least one, two and three solutions whenever the parameters λ and μ belong to certain positive intervals. The main tools are critical point theorems established in [5, 6, 7]. Here, as an example, we present a special case of our results.

Theorem 1.1 *Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function satisfying*

$$\lim_{x \rightarrow 0^+} \frac{f(x)}{x^2} = +\infty. \tag{1.2}$$

Then, for each $\lambda \in (0, \lambda^)$, where*

$$\lambda^* = \frac{c^2 \varepsilon_1}{2(b-a) \max_{|x| \leq c} \int_0^x f(s) \, ds}$$

for $c > 0$, the problem $(D_{\lambda,0}^{f,g,0})$ admits at least one non-trivial solution. (The constant ε_1 will be specified later.)

2 Preliminaries

We first introduce some basic notations. Let

$$E = \{u = \{u(t)\}_{t=a+1}^{b+1} : u(t) \in \mathbb{R}\}.$$

Then, E is a $(b - a + 1)$ -dimensional Hilbert space under the following inner product and norm

$$(u, v) = \sum_{t=a+1}^{b+1} u(t)v(t), \quad \|u\| = \left(\sum_{t=a+1}^{b+1} |u(t)|^2 \right)^{\frac{1}{2}}, \quad u, v \in E.$$

Clearly, the following inequality is true

$$\max_{t \in [a+1, b+1]} |u(t)| \leq \|u\|. \tag{2.1}$$

For $t \in [a + 1, b + 1]_{\mathbb{Z}}$ and $x \in \mathbb{R}$ set

$$F(t, x) = \int_0^x f(t, s) \, ds, \quad G(t, x) = \int_0^x g(t, s) \, ds, \quad H(x) = \int_0^x h(s) \, ds.$$

We define the operators $K, T, A_\lambda: E \rightarrow E$, respectively, by

$$Ku(t) = \sum_{k=a+1}^{b+1} G(t, k)u(k), \quad Tu(t) = f(t, u(t)) + \frac{\mu}{\lambda}g(t, u(t)) + \frac{1}{\lambda}h(u(t)),$$

$$A_\lambda = \lambda KT, \quad u \in E, \quad t \in [a + 1, b + 1]_{\mathbb{Z}}.$$

Since E is a $(b - a + 1)$ -dimensional Hilbert space and f, g are continuous in their second variable and $h: \mathbb{R} \rightarrow \mathbb{R}$ is a strictly monotone Lipschitz continuous function, the operators K and T are continuous. Consequently, $A_\lambda: E \rightarrow E$ is completely continuous.

Lemma 2.1 ([10, Lemma 2.1]) *Let $v \in E$ and $i \in \{1, 2\}$ be fixed. Also, let r_1, r_2 be the roots of the polynomial $P(r) = r^2 + \eta r - \zeta$. By the assumption on η and ζ , it follows that $r_1 \geq r_2 > -4 \sin^2 \frac{\pi}{2(b-a+2)}$. Then, the problem*

$$\begin{cases} -\Delta^2 u(t-1) + r_i u(t) = v(t), & t \in [a+1, b+1]_{\mathbb{Z}}, \\ u(a) = 0, \quad u(b+2) = 0, \end{cases}$$

has a unique solution

$$u(t) = \sum_{k=a+1}^{b+1} \mathbb{G}_i(t, k)v(k), \quad t \in [a, b + 2]_{\mathbb{Z}},$$

where $\mathbb{G}_i(t, k)$ is given by

$$\mathbb{G}_i(t, k) = \frac{1}{\rho(1, 0)\rho(b + 2, a)} \begin{cases} \rho(t, a)\rho(b + 2, k), & a \leq t \leq k \leq b + 1, \\ \rho(k, a)\rho(b + 2, t), & a + 1 \leq k \leq t \leq b + 2, \end{cases} \quad (2.2)$$

with

(i) $\rho(t, k) = \sin \varphi(t - k)$ and $\varphi = \arctan \frac{\sqrt{-r_i(r_i + 4)}}{2 + r_i}$, when $-4 \sin^2 \frac{\pi}{2(b - a + 2)} < r_i < 0$,

(ii) $\rho(t, k) = t - k$, when $r_i = 0$,

(iii) $\rho(t, k) = \iota^{t-k} - \iota^{t-k}$ and $\iota = \frac{r_i + 2 + \sqrt{r_i(r_i + 4)}}{2}$, when $r_i > 0$.

Lemma 2.2 ([10, Lemma 2.2]) Let $w \in E$ be fixed. Then, the following linear discrete fourth-order boundary value problem

$$\begin{cases} \Delta^4 u(t - 2) + \eta \Delta^2 u(t - 1) - \zeta u(t) = w(t), & t \in [a + 1, b + 1]_{\mathbb{Z}}, \\ u(a) = \Delta^2 u(a - 1) = 0, \quad u(b + 2) = \Delta^2 u(b + 1) = 0, \end{cases}$$

has a unique solution $u = \{u(t)\}_{t=a-1}^{b+3}$ with

$$\begin{aligned} u(t) &= \sum_{k=a+1}^{b+1} \left(\sum_{s=a+1}^{b+1} \mathbb{G}_1(t, s)\mathbb{G}_2(s, k) \right) w(k) \\ &= \sum_{k=a+1}^{b+1} \left(\sum_{s=a+1}^{b+1} \mathbb{G}_2(t, s)\mathbb{G}_1(s, k) \right) w(k), \quad t \in [a + 1, b + 1]_{\mathbb{Z}}. \end{aligned}$$

Lemma 2.3 ([10, Lemma 2.3]) The linear continuous operator $K: E \rightarrow E$ is symmetric, i.e., $(Ku, v) = (u, Kv)$ for all $u, v \in E$.

Lemma 2.4 ([10, Lemma 2.4]) The linear continuous operator $K: E \rightarrow E$ has $(b - a + 1)$ eigenvalues

$$\frac{1}{\varepsilon_1}, \frac{1}{\varepsilon_2}, \dots, \frac{1}{\varepsilon_{b-a+1}}$$

with the corresponding orthonormal eigenfunctions $e_1, e_1, \dots, e_{b-a+1}$, where $e_k = \{e_k(t)\}_{t=a+1}^{b+1}$ and

$$e_k(t) = \sqrt{\frac{2}{b - a + 2}} \sin \frac{t - a}{b - a + 2} k\pi, \quad t \in [a + 1, b + 1]_{\mathbb{Z}},$$

for $k = 1, 2, \dots, b - a + 1$. In addition, the algebraic multiplicity of each eigenvalue is 1.

By Lemmas 2.1 and 2.2, we have $\mathbb{G}_i(t, k) > 0$ and $\mathbb{G}_i(t, k) = \mathbb{G}_i(k, t)$ for all $t, k \in [a+1, b+1]_{\mathbb{Z}}$ and $i = 1, 2$. Let

$$\mathbb{G}(t, k) = \sum_{s=a+1}^{b+1} \mathbb{G}_1(t, s)\mathbb{G}_2(s, k), \quad t, k \in [a+1, b+1]_{\mathbb{Z}}.$$

Clearly, $\mathbb{G}(t, k) = \mathbb{G}(k, t)$ for all $t, k \in [a+1, b+1]_{\mathbb{Z}}$.

Remark 2.5 From Lemma 2.2, it can easily be seen that the fixed point $u = \{u(t)\}_{t=a+1}^{b+1} \in E$ of A_λ is exactly the solution $u = \{u(t)\}_{t=a-1}^{b+3}$ of $(D_{\lambda, \mu}^{f, g, h})$, where $u(a-1) = -u(a+1)$, $u(a) = 0$, $u(b+2) = 0$, $u(b+3) = -u(b+1)$.

Again from Lemmas 2.3 and 2.4, we obtain that $Ku(t) = \frac{1}{\varepsilon}u(t)$ for $u \in E$, $t \in [a+1, b+1]_{\mathbb{Z}}$, where $\frac{1}{\varepsilon} = \frac{1}{\varepsilon_k}$. From [10] we also know that

$$\varepsilon_k = 2 \cos \frac{2k\pi}{b-a+2} + (2\eta - 8) \cos \frac{k\pi}{b-a+2} + 6 - 2\eta - \xi, \quad k \in [1, b-a+1]_{\mathbb{Z}},$$

and

$$0 < \varepsilon_1 < \dots < \varepsilon_{b-a+1}. \tag{2.3}$$

Moreover, the operator K has a unique inverse defined by $K^{-1}u = \varepsilon u$ for $u \in E$, where $\varepsilon = \varepsilon_k$, $k \in [1, b-a+1]_{\mathbb{Z}}$.

For $u \in E$ we define the functionals $\Phi, \Psi: E \rightarrow \mathbb{R}$ by

$$\Phi(u) = \frac{1}{2}(K^{-1}u, u) - \sum_{t=a+1}^{b+1} H(u(t)), \tag{2.4}$$

and

$$\Psi(u) = \sum_{t=a+1}^{b+1} \left[F(t, u(t)) + \frac{\mu}{\lambda} G(t, u(t)) \right]. \tag{2.5}$$

For every $\lambda > 0$ put $I_\lambda(u) = \Phi(u) - \lambda\Psi(u)$. Then, I_λ is continuously Fréchet differentiable and its derivative at the point $u \in E$ is

$$\begin{aligned} I'_\lambda(u) &= \Phi'(u) - \lambda\Psi'(u) \\ &= K^{-1}u - \sum_{t=a+1}^{b+1} h(u(t)) - \lambda \sum_{t=a+1}^{b+1} \left[f(t, u(t)) + \frac{\mu}{\lambda} g(t, u(t)) \right] \\ &= K^{-1}u - \lambda Tu. \end{aligned} \tag{2.6}$$

Definition 2.6 Let Φ and Ψ be two continuously differentiable functionals defined on a real Banach space E , and fix $r \in \mathbb{R}$. The functional $I = \Phi - \Psi$ is said to satisfy the Palais–Smale condition cut off above at r (in short $(P.S.)^r$) if any sequence $\{u_n\}_{n \in \mathbb{N}}$ in E such that

- (a) $\{I(u_n)\}$ is bounded,
- (b) $\lim_{n \rightarrow \infty} \|I'(u_n)\|_{E^*} = 0$,
- (c) $\Phi(u_n) < r$ for each $n \in \mathbb{N}$,

has a convergent subsequence.

Remark 2.7 Since the operator equation $u = A_\lambda u$ is equivalent to the operator equation $K^{-1}u = \lambda Tu$, we know that every critical point of the functional I_λ in E is a solution of $(D_{\lambda,\mu}^{f,g,h})$. Therefore, it will be enough only to find the critical points of the functional I_λ in E .

The following theorem is a particular case of [4, Theorem 5.1], and it is the main tool we are going to use in the next section.

Theorem 2.8 (see [5, Theorem 2.3]) Let E be a real Banach space, and let $\Phi, \Psi: E \rightarrow \mathbb{R}$ be two continuously differentiable functionals such that $\inf_{x \in E} \Phi(x) = \Phi(0) = \Psi(0) = 0$. Assume that there exist $r > 0$ and $\bar{x} \in E$ with $0 < \Phi(\bar{x}) < r$ such that

$$(a_1) \quad \frac{\sup_{\Phi(x) \leq r} \Psi(x)}{r} < \frac{\Psi(\bar{x})}{\Phi(\bar{x})},$$

(a₂) for each

$$\lambda \in \left(\frac{\Phi(\bar{x})}{\Psi(\bar{x})}, \frac{r}{\sup_{\Phi(x) \leq r} \Psi(x)} \right)$$

the functional $I_\lambda := \Phi - \lambda\Psi$ satisfies $(P.S.)^r$ condition.

Then, for each

$$\lambda \in \left(\frac{\Phi(\bar{x})}{\Psi(\bar{x})}, \frac{r}{\sup_{\Phi(x) \leq r} \Psi(x)} \right)$$

there is $x_{0,\lambda} \in \Phi^{-1}((0, r))$ such that $I'_\lambda(x_{0,\lambda}) = 0$ and $I_\lambda(x_{0,\lambda}) \leq I_\lambda(x)$ for all $x \in \Phi^{-1}((0, r))$.

Other next tool is the following abstract result.

Theorem 2.9 ([5, Theorem 3.2]) Let E be a real Banach space, and let $\Phi, \Psi: E \rightarrow \mathbb{R}$ be two continuously differentiable functionals such that Φ is bounded from below and $\Phi(x) = \Phi(0) = \Psi(0) = 0$. Fix $r > 0$ and assume that for each

$$\lambda \in \left(0, \frac{r}{\sup_{u \in \Phi^{-1}((-\infty, r))} \Psi(u)} \right)$$

the functional $I_\lambda = \Phi - \lambda\Psi$ satisfies $(P.S.)$ condition and is unbounded from below. Then, for each

$$\lambda \in \left(0, \frac{r}{\sup_{u \in \Phi^{-1}((-\infty, r))} \Psi(u)} \right)$$

the functional I_λ admits two distinct critical points.

Finally, we recall the following result of Bonanno and Marano (see [7]), stated here in a convenient form.

Theorem 2.10 ([7, Theorem 3.6]) *Let E be a reflexive real Banach space. Moreover, let $\Phi: E \rightarrow \mathbb{R}$ be a coercive, continuously differentiable and sequentially weakly lower semi-continuous functional whose continuous derivative admits a continuous inverse on E^* . Also, let $\Psi: E \rightarrow \mathbb{R}$ be a continuously differentiable functional with compact derivative such that*

$$\inf_{x \in E} \Phi(x) = \Phi(0) = \Psi(0).$$

Assume that there exist $r > 0$ and $\bar{x} \in E$ with $r < \Phi(\bar{x})$ such that

$$(b_1) \quad \frac{\sup_{\Phi(x) \leq r} \Psi(u)}{r} < \frac{\Psi(\bar{x})}{\Phi(\bar{x})},$$

(b₂) for each

$$\lambda \in \Lambda := \left(\frac{\Phi(\bar{x})}{\Psi(\bar{x})}, \frac{r}{\sup_{\Phi(x) \leq r} \Psi(u)} \right)$$

the function $\Phi - \lambda\Psi$ is coercive.

Then, for each $\lambda \in \Lambda$ the functional $\Phi - \lambda\Psi$ has at least three distinct critical points in E .

Remark 2.11 *Throughout the abstract results, E denotes a real Banach space. In the present work, however, E specifically represents a finite-dimensional Hilbert space. This distinction causes no difficulty, since every finite-dimensional Hilbert space is naturally a Banach space under its induced norm. Consequently, all cited theoretical results remain valid in our framework.*

3 Main results

In this section, we deal with the existence of one solution for the problem $(D_{\lambda, \mu}^{f, g, h})$. For a real parameter $c > 0$ set

$$F_{\max} = \sum_{t=a+1}^{b+1} \max_{|x| \leq c} F(t, x),$$

$$G_{\max} = \sum_{t=a+1}^{b+1} \max_{|x| \leq c} G(t, x),$$

$$\sigma_1 = \left| \frac{c^2(\varepsilon_1 - L) - 2\lambda F_{\max}}{2G_{\max}} \right|,$$

$$\sigma_2 = \left| \frac{(\varepsilon_{b+a+1} + L)(b - a + 1)d^2 - 2\lambda F_{\max}}{2 \min\{0, G_{\max}\}} \right|,$$

$$\sigma_3 = \frac{\varepsilon_1}{\max\left\{0, 4 \limsup_{|x| \rightarrow +\infty} \frac{G_{\max}}{x^2}\right\}},$$

$$\sigma = \min\{\sigma_1, \sigma_2, \sigma_3\}.$$

Now, we have the following theorem.

Theorem 3.1 Let $f: [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function. Moreover, assume that

$$(j_2) \limsup_{x \rightarrow 0^+} \frac{\inf_{t \in [a+1, b+1]_{\mathbb{Z}}} F(t, x)}{x^2} = +\infty.$$

Then, setting

$$\lambda^* = \frac{(\varepsilon_1 - L)c^2}{2F_{\max}},$$

where c is a positive constant and ε_1 is given in Lemma 2.4, for each parameter $\lambda \in (0, \lambda^*)$ and for each continuous function $g: [a + 1, b + 1] \times \mathbb{R} \rightarrow \mathbb{R}$ satisfying

$$\limsup_{|x| \rightarrow +\infty} \frac{\sum_{t=a+1}^{b+1} G(t, x)}{x^2} < +\infty, \tag{3.1}$$

and any $\mu \in [0, \sigma)$, the problem $(D_{\lambda, \mu}^{f, g, h})$ admits at least one non-trivial solution.

Proof. Our aim is to apply Theorem 2.8 to the space E , endowed with its standard norm, and to the functionals $\Phi, \Psi: E \rightarrow \mathbb{R}$ defined in (2.4) and (2.5), respectively. We prove that the functionals Φ and Ψ satisfy the assumptions of Theorem 2.8. By the definitions of Φ and Ψ , it is clear that both functionals continuously differentiable. Moreover, since h is strictly monotone, we get that the continuous derivative of Φ admits a continuous inverse on E^* . Now, we claim that the continuous derivative of Ψ is compact. Assume that there is a constant $M_1 > 0$ such that $\|u\| \leq M_1$. Combining this with the continuity of f and g , and arguing as in [21], we conclude that $\Psi'(u)$ is uniformly bounded. Since f and g are continuous, they are uniformly continuous on $[a + 1, b + 1]_{\mathbb{Z}} \times [-M_1, M_1]$. In addition, since Ψ is continuous, it is also sequentially upper semi-continuous. We observe that Φ is sequentially lower semi-continuous. Moreover, since $\sum_{t=a+1}^{b+1} H(u(t))$ is continuous, putting $M(u) = \sum_{t=a+1}^{b+1} H(u(t))$ for $u \in E$ will lead to $M(u_n) \rightarrow M(u)$ as $u_n \rightarrow u$ in E . On the other hand, since E is a finite-dimensional Hilbert space and the inner product is continuous with respect to norm convergence in both variables, it follows that

$$\liminf_{n \rightarrow \infty} \Phi(u_n) = \liminf_{n \rightarrow \infty} \frac{(K^{-1}u_n, u_n)}{2} - \lim_{n \rightarrow \infty} M(u_n) \geq (K^{-1}u_n, u_n) - Mu = \Phi(u).$$

Also, as shown in [21], the functional Φ is coercive and

$$\frac{\varepsilon_1 - L}{2} \|u\|^2 \leq \Phi(u) \leq \frac{\varepsilon_{b-a+1} + L}{2} \|u\|^2.$$

Set

$$r = \frac{\varepsilon_1 - L}{2} c^2.$$

From (2.1), arguing as in [21], we have

$$\sup_{\Phi(u) \leq 1} \Psi(u) \leq \sum_{t=a+1}^{b+1} \max_{|x| \leq c} F(t, x) + \frac{\mu}{\lambda} \sum_{t=a+1}^{b+1} \max_{|x| \leq c} G(t, x) = F_{\max} + \frac{\mu}{\lambda} G_{\max}, \tag{3.2}$$

which implies that

$$\frac{\sup_{\Phi(u) \leq 1} \Psi(u)}{r} \leq \frac{2}{c^2(\varepsilon_1 - L)} \left(F_{\max} + \frac{\mu}{\lambda} G_{\max} \right).$$

If $G_{\max} \leq 0$, by the fact that

$$\lambda < \frac{(\varepsilon_1 - L)c^2}{2F_{\max}},$$

we obtain

$$\frac{\sup_{\Phi(u) \leq 1} \Psi(u)}{r} \leq \frac{2F_{\max}}{(\varepsilon_1 - L)c^2} < \frac{1}{\lambda}. \quad (3.3)$$

If $G_{\max} > 0$, since $\lambda \in \Lambda$, we get

$$\frac{\sup_{\Phi(u) \leq 1} \Psi(u)}{r} \leq \frac{2F_{\max}}{(\varepsilon_1 - L)c^2} + \frac{2G_{\max}}{(\varepsilon_1 - L)c^2} \cdot \frac{\left| \frac{(\varepsilon_1 - L)c^2 - 2\lambda F_{\max}}{2G_{\max}} \right|}{\lambda} = \frac{1}{\lambda}. \quad (3.4)$$

By choosing $\bar{u} = d$ and using (j₁), together with the condition $c^2 < (b - a + 1)d^2$, we obtain

$$\Phi(\bar{u}) \geq \frac{\varepsilon_1 - L}{2} c^2 = r.$$

Furthermore, we have

$$\frac{\Psi(\bar{u})}{\Phi(\bar{u})} \geq \frac{2 \sum_{t=a+1}^{b+1} F(t, d)}{(\varepsilon_{b-a+1} + L)(b - a + 1)d^2} + \frac{2\mu \sum_{t=a+1}^{b+1} G(t, d)}{\lambda(\varepsilon_{b-a+1} + L)(b - a + 1)d^2}.$$

If $G_{\max} > 0$, from [21] we get

$$\frac{\Psi(\bar{u})}{\Phi(\bar{u})} \geq \frac{2 \sum_{t=a+1}^{b+1} F(t, d)}{(\varepsilon_{b-a+1} + L)(b - a + 1)d^2} > \frac{1}{\lambda}. \quad (3.5)$$

If $G_{\max} < 0$, since $\lambda \in \Lambda$, we obtain

$$\frac{\Psi(\bar{u})}{\Phi(\bar{u})} \geq \frac{1}{\lambda}. \quad (3.6)$$

Therefore, from (3.3)–(3.6), condition (a₁) of Theorem 2.8 holds. Also, from (2.1), (2.6) and the results in [21], we can see that for every $u \in E$ there exists a positive constant δ_μ such that

$$\sum_{t=a+1}^{b+1} G(t, u(t)) \leq \frac{\varepsilon_1}{4\mu} \|u\|^2 + \delta_\mu. \quad (3.7)$$

Moreover, from condition (j₂), we have $\sum_{t=a+1}^{b+1} F(t, u(t)) \leq z$ for $(t, x) \in [a + 1, b + 1] \times \mathbb{R}$, and hence

$$\lambda \sum_{t=a+1}^{b+1} F(t, u(t)) \leq \frac{(\varepsilon_1 - L)c^2 z}{2F_{\max}}. \quad (3.8)$$

We also obtain

$$\Phi(u) - \lambda\Psi(u) \geq \frac{\varepsilon_1 - 2L}{4\chi} \|u\|^2 - \mu\delta_\mu - \frac{(\varepsilon_1 - L)c^2 z}{2F_{\max}},$$

which means that condition (a₂) of Theorem 2.8 holds. Hence, for each

$$\lambda \in \left(\frac{\Phi(\bar{x})}{\Psi(\bar{x})}, \frac{1}{\sup_{\Phi(x) \leq 1} \Psi(x)} \right)$$

Theorem 2.8 guarantees that u is a non-trivial solution of the problem $(D_{\lambda, \mu}^{f, g, h})$. □

Remark 3.2 *Theorem 1.1 in the introduction immediately follows from Theorem 3.1.*

Example 3.3 *Let $\eta = \xi = 0$, $a = 0$ and $b = 4$. Consider the following discrete fourth-order problem*

$$\begin{cases} \Delta^4 u(t-2) = \lambda f(t, u(t)) + \mu g(t, u(t)) + h(u(t)), & t \in [1, 5]_{\mathbb{Z}}, \\ u(0) = \Delta^2 u(-1) = 0, \quad u(6) = \Delta^2 u(5) = 0, \end{cases} \quad (3.9)$$

where

$$f(t, x) = t\sqrt[3]{x^4}, \quad g(t, x) = 2tx, \quad h(x) = \arctan 0.5x, \quad t \in [1, 5]_{\mathbb{Z}}, \quad x \in \mathbb{R}.$$

Taking into account that $\varepsilon_1 = 0.8$, $\varepsilon_5 = 1.2$, $L = 0.3$ and $c = 2$, it is obvious that f, g are two continuous functions and h is a monotone Lipschitz continuous function. Moreover, we have

$$\limsup_{x \rightarrow 0^+} \frac{\frac{3}{7}x^{\frac{7}{3}}}{x^2} = +\infty,$$

and

$$\lambda^* = \frac{1}{\frac{45}{7} \cdot 2^{\frac{7}{3}}}.$$

Also, since

$$\sigma_1 = \left| \frac{2 - \frac{90}{7} \cdot 2^{\frac{7}{3}} \lambda}{120} \right| \quad \text{and} \quad \sigma_3 = \frac{0.8}{60} = 0.013\bar{3},$$

it follows that

$$\sigma = \min\{\sigma_1, \sigma_3\}.$$

Finally, we have

$$\limsup_{|x| \rightarrow +\infty} \frac{\sum_{t=a+1}^{b+1} G(t, x)}{x^2} = 15 < +\infty. \quad (3.10)$$

So, condition (j₂) of Theorem 3.1 holds. Therefore, for each $\lambda \in (0, 0.048)$ and $\mu \in [0, \sigma)$ the problem (3.9) admits at least one non-trivial solution.

4 Existence of two solutions

In this section, our goal is to obtain the existence of two distinct solutions for the problem $(D_{\lambda, \mu}^{f, g, h})$. The following result is obtained by applying Theorem 2.9.

Theorem 4.1 *Let $f: [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function. Assume that*

- (j₃) *there exist constants $\chi > 2$ and $r > 0$ such that $0 < \chi F(t, x) < x f(t, x)$ for all $t \in [a + 1, b + 1]_{\mathbb{Z}}$ and $|x| \geq r$.*

Then, for each $\lambda \in (0, \lambda^*)$ and for any continuous function $g: [a + 1, b + 1] \times \mathbb{R} \rightarrow \mathbb{R}$ satisfying

$$\limsup_{|x| \rightarrow +\infty} \frac{\sum_{t=a+1}^{b+1} G(t, x)}{x^2} < +\infty, \quad (4.1)$$

and for any $\mu \in [0, \sigma)$, where λ^* and σ are as in Theorem 3.1, the problem $(D_{\lambda, \mu}^{f, g, h})$ admits at least two distinct solutions.

Proof. We apply Theorem 2.9 to the space E , endowed with its standard norm, and to the functionals $\Phi, \Psi: E \rightarrow \mathbb{R}$ defined in (2.4) and (2.5). Integrating condition (j₃), there exist constants $\alpha_1, \beta_1 > 0$ such that

$$F(t, x) \geq \alpha_1|x|^\chi - \beta_1$$

for all $(t, x) \in [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R}$. For a fixed $\bar{u} \in E \setminus \{\theta\}$ and any $x > 1$, we have

$$I_\lambda(x\bar{u}) \leq \frac{1}{2}x^2\|\bar{u}(t)\|^2 - \lambda\alpha_1x^\chi \sum_{t=a+1}^{b+1} |\bar{u}(t)|^\chi + (b - a + 1)\lambda\beta_1.$$

Since $\chi > 2$, this shows that I_λ is unbounded from below. By standard arguments, the functional $I_\lambda = \Phi - \lambda\Psi$ satisfies (P.S.) condition (see, for instance, [20]). Therefore, all assumptions of Theorem 2.9 are satisfied. In conclusion, for each $\lambda \in (0, \lambda^*)$ the functional I_λ admits two distinct critical points, which are the solutions of the problem $(D_{\lambda,\mu}^{f,g,h})$. \square

Remark 4.2 We observe that, if $f(t, 0) \neq 0$, then Theorem 4.1 ensures the existence of two non-trivial solutions for the problem $(D_{\lambda,\mu}^{f,g,h})$. Moreover, we point out that in most works concerning the existence of solutions for the problem $(D_{\lambda,\mu}^{f,g,h})$, the following condition is assumed

$$\limsup_{x \rightarrow 0^+} \frac{\inf_{t \in [a+1, b+1]_{\mathbb{Z}}} F(t, x)}{x^2} = 0.$$

It is easily seen that this condition is incompatible with the assumption $f(t, 0) \neq 0$.

Example 4.3 Consider the following discrete fourth-order problem

$$\begin{cases} \Delta^4 u(t - 2) = \lambda f(t, u(t)) + \mu g(t, u(t)) + h(u(t)), & t \in [2, 7]_{\mathbb{Z}}, \\ u(1) = \Delta^2 u(0) = 0, & u(8) = \Delta^2 u(7) = 0, \end{cases} \tag{4.2}$$

where

$$f(t, x) = a + b\sqrt[5]{x^6}, \quad g(t, x) = \frac{x}{t}, \quad h(x) = \arctan 0.5x, \quad t \in [2, 7]_{\mathbb{Z}}, |x| \geq r.$$

Clearly, f and g are two continuous functions and h is a monotone Lipschitz continuous function. We see that $F(t, x) = ax + \frac{5b}{11}x^{\frac{11}{5}}$ and $G(t, x) = 7$. Then, for a fixed r and $x \leq -r$ we have

$$\begin{aligned} xf(t, x) - \chi F(t, x) &= ax + bx\sqrt[5]{x^6} - \chi \left(ax + \frac{5b}{11}x^{\frac{11}{5}} \right) \\ &= ax(1 - \chi) + bx^{\frac{11}{5}} \left(1 - \frac{5}{11}\chi \right) \\ &= |x|(a(\chi - 1) + b|x|^{\frac{6}{5}} \left(\frac{5}{11}\chi - 1 \right)) > 0. \end{aligned}$$

In addition, if $x \geq r$ for

$$r^{\frac{5}{6}} > \frac{a(\chi - 1)}{b(1 - \frac{5}{11}\chi)},$$

we have

$$\begin{aligned} xf(t, x) - \chi F(t, x) &= ax + bx\sqrt[5]{x^6} - \chi\left(ax + \frac{5b}{11}x^{\frac{11}{5}}\right) \\ &= ax(1 - \chi) + bx^{\frac{11}{5}}\left(1 - \frac{5}{11}\chi\right) \\ &\geq r\left((a(1 - \chi) + br^{\frac{6}{5}}\left(1 - \frac{5}{11}\chi\right))\right) > 0. \end{aligned}$$

Then, condition (j₃) is satisfied. Hence, the problem (4.2) admits at least two distinct solutions.

5 Existence of three solutions

In this section, we deal with the existence of at least three solutions for the problem $(D_{\lambda, \mu}^{f, g, h})$.

Theorem 5.1 Let $f: [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function. Assume that

(j₄) there exist $c_1 \in [0, +\infty)$ and $1 < \alpha < 2$ such that $F(t, x) \leq c_1(1 + |x|^\alpha)$ for all $(t, x) \in [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R}$,

(j₅) $F(t, x) \geq 0$ for each $(t, x) \in [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R}^+$,

(j₆) there exist $r > 0$ and $\iota > 0$ with $r < \frac{1}{2}(\varepsilon_1 - L)(b - a + 1)\iota^2$ such that

$$\omega := \frac{2F_{\max}}{r(\varepsilon_1 - L)c^2} < \frac{\inf_{t \in [a+1, b+1]_{\mathbb{Z}}} F(t, \iota)}{\frac{1}{2}(\varepsilon_1 - L)(b - a + 1)\iota^2}.$$

Also, let $g: [a + 1, b + 1]_{\mathbb{Z}} \times \mathbb{R} \rightarrow \mathbb{R}$. Then, for every

$$\lambda \in \left(\frac{\frac{1}{2}(\varepsilon_1 - L)(b - a + 1)\iota^2}{\inf_{t \in [a+1, b+1]_{\mathbb{Z}}} F(t, \iota)}, \frac{1}{\omega} \right)$$

and for any $\mu \in [0, \sigma)$, where σ is as in Theorem 3.1, the problem $(D_{\lambda, \mu}^{f, g, h})$ admits at least three solutions.

Proof. Our aim is to apply Theorem 2.10 to the space E , endowed with its standard norm, and to the functionals $\Phi, \Psi: E \rightarrow \mathbb{R}$ defined in (2.4) and (2.5), respectively. As shown before, the functionals Φ and Ψ satisfy the regularity assumptions required by Theorem 2.10. Now, let $\nu \in E$ be defined by

$$\nu(t) = \iota. \tag{5.1}$$

We have

$$\frac{\varepsilon_1 - L}{2}(b - a + 1)\iota^2 < \Phi(\nu) < \frac{\varepsilon_{b-a+1} + L}{2}(b - a + 1)\iota^2.$$

By (j₅),

$$\Psi(\nu) \geq \sum_{t=1}^{b+1} \left[F(t, \nu(t)) + \frac{\mu}{\lambda} G(t, \nu(t)) \right] \geq \inf_{t \in [a+1, b+1]_{\mathbb{Z}}} \left[F(t, \iota) + \frac{\mu}{\lambda} G(t, \iota) \right],$$

so that

$$\frac{\Psi(\nu)}{\Phi(\nu)} \geq \frac{\inf_{t \in [a+1, b+1]} \Psi(t)}{\frac{1}{2}(\varepsilon_1 - L)(b - a + 1)\iota^2}. \tag{5.2}$$

As $r < \frac{1}{2}(\varepsilon_1 - L)(b - a + 1)\iota^2$, we have $r < \Phi(\nu)$. Also, from (2.1) it follows that

$$\sum_{t=a+1}^{b+1} |u(t)|^\alpha < \sum_{t=a+1}^{b+1} \max_{t \in [a+1, b+1]_{\mathbb{Z}}} |u(t)|^\alpha \leq \|u\|^\alpha \tag{5.3}$$

for every $u \in E$. So, (5.3) implies that for each $u \in \Phi^{-1}((-\infty, r))$ we have

$$\begin{aligned} \Psi(u) &= \sum_{t=a+1}^{b+1} \left[F(t, u(t)) + \frac{\mu}{\lambda} G(t, u(t)) \right] \\ &\leq \sum_{t=a+1}^{b+1} c_1(1 + |u(t)|^\alpha) + \sum_{t=a+1}^{b+1} \frac{\mu}{\lambda} G(t, u(t)) \\ &\leq c_1(\|u\|^\alpha + (b - a + 2)) + \sum_{t=a+1}^{b+1} \frac{\mu}{\lambda} G(t, u(t)). \end{aligned}$$

From (j₆) and (5.2) we obtain

$$\frac{\sup_{\Phi(u) \leq r} \Psi(u)}{r} < \frac{\Psi(\nu)}{\Phi(\nu)}.$$

Hence, condition (b₁) of Theorem 2.10 is satisfied. Define $I_\lambda := \Phi - \lambda\Psi$. Then,

$$I_\lambda(u) \geq \frac{\|u\|^2}{2} - \lambda c_1(\|u\|^\alpha + (b - a + 2)) + \sum_{t=a+1}^{b+1} \mu G(t, u(t)),$$

which shows that I_λ is coercive. By above calculation, we have

$$\Lambda \subseteq \left(\frac{\Phi(\nu)}{\Psi(\nu)}, \frac{r}{\sup_{\Phi(u) \leq r} \Psi(u)} \right).$$

Theorem 2.10 ensures that for each $\lambda \in \Lambda$, the functional I_λ admits at least three critical points in E that are the solutions of the problem $(D_{\lambda, \mu}^{f, g, h})$. □

Remark 5.2 We observe that, if $f(t, 0) \neq 0$, then by Theorem 5.1, we obtain the existence of at least three non-zero solutions.

Example 5.3 We set $a = 1, b = 5, c = 4$, and $c_1 = 6$. Since

$$F(t, x) = \frac{x}{t} \geq 0 \quad \text{for } (t, x) \in [2, 6] \times [0, +\infty),$$

condition (j₅) of Theorem 5.1 is satisfied. Moreover, the inequality

$$\frac{x}{t} \leq 6(1 + |x|^\alpha)$$

ensures that condition (j_4) holds. Next, we take $L = 0.2$, $r = 10$, $\iota = 4$, $\varepsilon_1 = 0.5$, and $G(t, x) = x^2 + 3t$. Then, simple calculations give

$$\omega := \frac{1}{360} < \frac{2}{12}.$$

Also, since

$$\sigma_1 = \left| \frac{1.2 - \frac{2}{5}\lambda}{212} \right| \quad \text{and} \quad \sigma_3 = 0.5,$$

we obtain

$$\sigma = \min\{\sigma_1, \sigma_3\}.$$

Hence, for $\lambda \in (6, 360)$ and $\mu \in [0, \sigma)$, the problem $(D_{\lambda, \mu}^{f, g, h})$ admits at least three non-zero solutions.

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